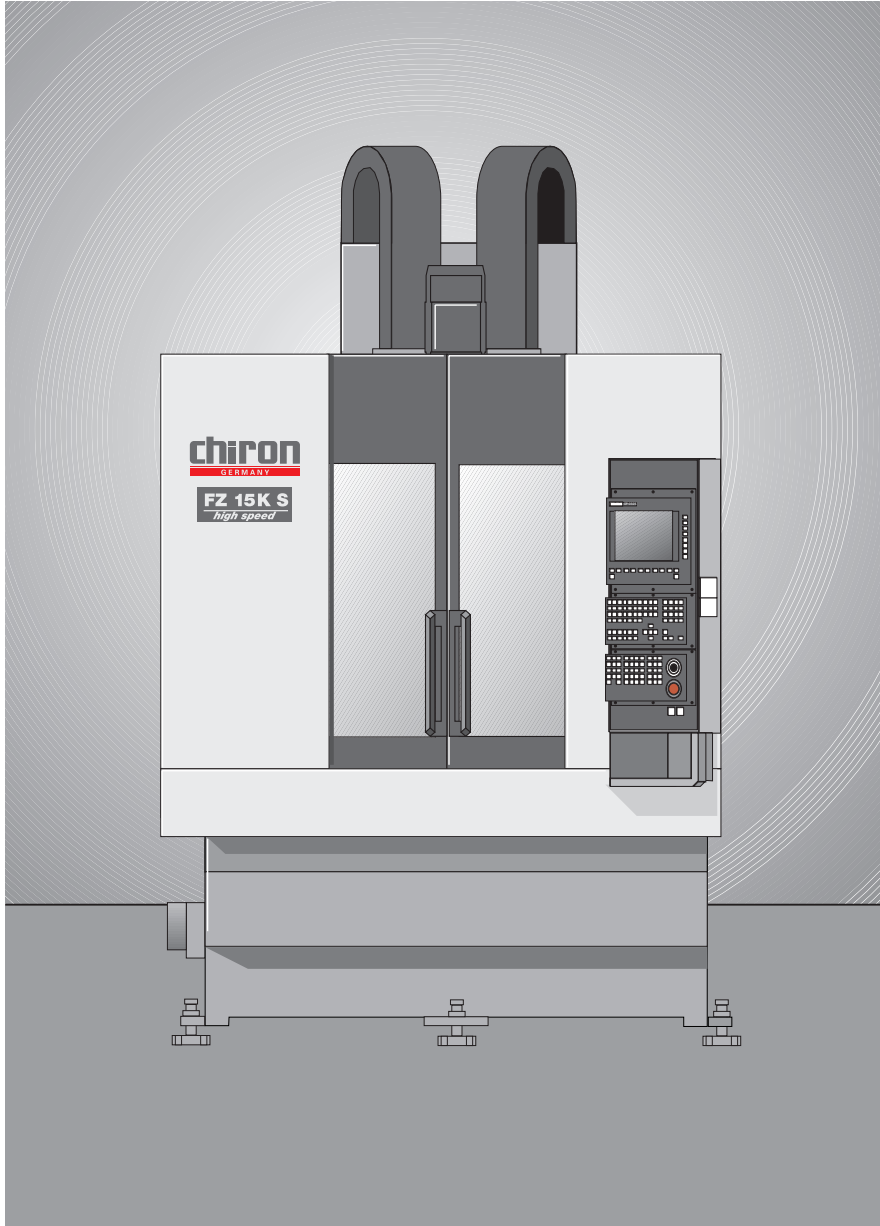


chiron

CNC Machining Centres



Datasheet

FZ 15K S

HSK-A 63

Tools 48

Chip-to-chip 2.4 s

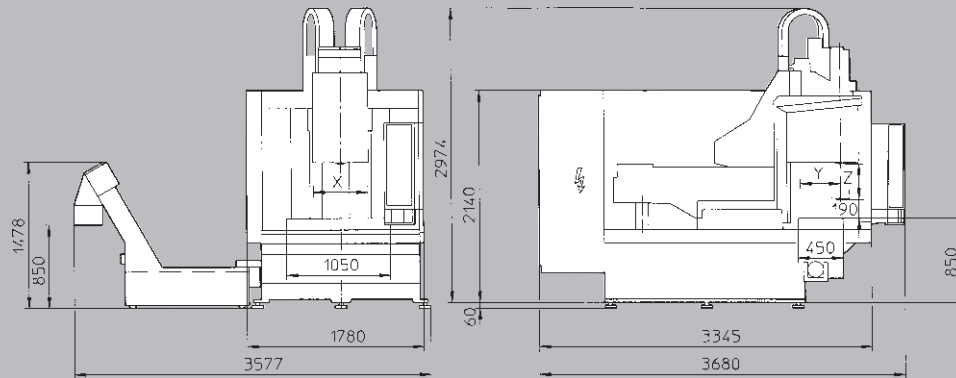
Spindle speed up to 20 000 rpm

Rapid up to 60 m/min

Acceleration up to 1.2 g

Seconds ahead

FZ 15K S



Technical data

Drilling capacity in ST 60 with HM drill	36 mm
Tapping	M 24
Milling capacity in ST 60	250 cm ³ /min
Tool storage capacity	48
Tool taper DIN 69893	HSK-A 63
Max. tool diameter	80 mm
If adjacent places are free	125 mm
Max. tool weight	10 kg
Tool change time	approx. 0.9 s
Chip-to-chip time	2.4 s
Spindle drive	14 kW
Infinitely variable speed range	20 - 12 000 rpm
Max. torque	90 Nm
Diameter front spindle bearing	65 mm
Tool clamping	mechanically locked
Distance spindle to column	90 - 495 mm
Distance spindle nose to table surface	190 - 550 mm
Travel X-axis	550 mm
Travel Y-axis	400 mm
Feed force X-axis, Y-axis	5 000 N
Travel Z-axis	360 mm
Feed force Z-axis	10 000 N
Rapid feed rate	40 m/min
Acceleration X-axis	0.5 g
Acceleration Y-axis	1.0 g
Acceleration Z-axis	1.2 g
Fixed table clamping surface	1 050 x 450 mm ²
T-Slots	2 x 18 H 12
Reference slot	18 H 8
Table load	500 kg
Chip conveyor, discharge height	850 mm
Coolant device, container capacity	500 l
Total connected power	approx. 19 kVA
Machine weight	approx. 5.0 t
Floor space	approx. 6.6 m ²
Air connection	6 bar

Options

High speed plus version

Basic machine with speed range 20 - 20 000 rpm

Higher spindle drive 28 kW

Speed range 20 - 12 000 rpm

Max. torque 180 Nm

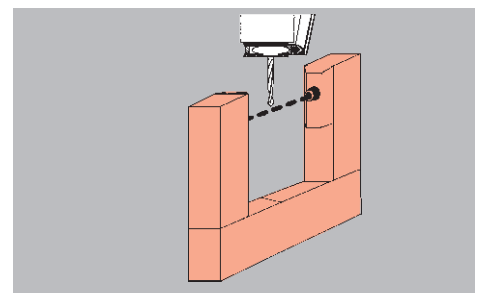
Drilling capacity in ST 60 with carbide drill 42 mm

Tapping M 30

Milling capacity in ST 60 500 cm³/min

NC rotary table NC rotary table with basic fixture Through the spindle coolant up to 70 bar Full enclosure with extraction Automatic doors Dry machining with minimal lubrication Thermocontrol Probes for workpiece and tool measurement Tool breakage monitoring and tool life management Direct path measuring system Multi-spindle head adaptor Workpiece transport and magazine equipment

Chiron-Laser-Control



Stationary 3-D probe system

